COMPARATIVE STUDY OF PARALLEL THINNING ALGORITHMS

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ABSTRACT:

The following paper deals with detailed comparative study of parallel thinning algorithms for skeletonization of images. The relative performance of the algorithms in regards to skeleton quality and rough iteration count is reported. It begins with a brief introduction to various algorithms included in the study, followed by the algorithm comparison in various fields, namely: number of iterations, thinness, sensitivity to noise and rotation.

INTRODUCTION TO VARIOUS ALGORITHMS:

Five algorithms are compared to gauge the relative performance of the algorithm in regards to skeleton quality and rough iteration count . If for pixel p, X(p) is equal to half the number of transition from a white pixel to a black & vice versa . N(p) is summation over n(j), j=1 to 8, neighbors of p.

- PSTA: Its based on Rutovitz crossing number and template matching. Full parallelism is achieved by an operator support larger than 3x3. The initial thinning criteria is X(p) = 1 and 1 < N(p) < 7. This is followed by 2 simple cleaning cycles are executed, after which the algorithm terminates
- HSCP: HSCP is also based on X(p). Its fully parallel with a higher operator support. It computes the edge status not only of p but of its S, E and SE neighbors as well. It then uses the values of its neighbors in conjunction with the edge values of those three neighbors in simple logical conditions to determine final thinning status. The algorithm terminates when no pixels are thinned between consecutive iteration.
- CWSI: CWSI function by using a set of 10 windows. A pixel is thinned if it matches any of the 8, 3x3 thinning windows, unless it also matches the 3x4 or the 4x3 restoring window. The algorithm terminates when no pixels are thinned between consecutive iterations.
- AFP3: AFP3 is based on X(p), but unlike HSCP and PSTA, it accepts N(p)=7 as an edge when the single white pixels is one of the connected neighbors. It uses 3 restoring windows to prevent disconnectivities and 2 additional thinning windows to eliminate step skeletons. The algorithm terminates when no pixels are thinned between consecutive iterations.
- JC: It uses a set of 30 thinning and restoring windows, labeled A(1) to A(30) ranging in size from 3x3 to 5x5. The 4 largest windows are unique in that they check for the interior of right angles. This alleviates the problem of skeletons loosing mediality by cutting sharp corners, a characteristic which is common to most thinning algorithms.

COMPARISION RESULTS:

- Number of Iterations: The discrepancy between different algorithms in number of iterations needed to arrive a final skeleton varies from image to be thinned. On the whole JC leads slightly (i.e. takes fewer iterations), PSTA and AFP3 require the same number of iterations and CWSI algorithm lag by a few. When 90° corners aligned with the grid are involved the JC algorithm tends to take fewer iterations than PSTA and AFP3 due to its A(17-20) windows.
- Thinness: Ideal skeleton is one pixel wide. This lead a minor ambiguity in the case of a diagonal line. Ideally ,diagonally adjacent pixels are connected to form a minimal diagonal line (Fig. 1). While the zigzag or step skeleton gives rise to ambiguity. Of the 5 algorithms PSTA, HSCP, CWSI, produce step skeletons while AFP3 and JC produce 8 connected diagonal lines. To address this is the reason the cleaning stages were developed for PSTA. If a perfectly connected skeleton is not required PSTA by itself gives a skeleton with good isotropy and noise immunity.
- Sensitivity to Noise: Noise arises from equipment limitations, interference, extraneous foreign elements and the like. Here noise is divided into 4 steps: irregular edges, positive edge noise, negative edge noise and internal noise. Irregular edges are an attribute of the image itself. The image has a very strong intuitive skeleton combined with a wide variety of edge configurations. CWSI shows the worst noise sensitivity, followed by AFP3. JC does not show any noise and produces the best skeleton, followed by PSTA. An extra black pixel extending beyond the image's border, referred to as the positive edge noise, or as a pixel missing from the border, referred to as negative edge noise. None of the algorithms are affected much by the positive edge noise. The JC and AFP3 algorithms are the most sensitive to the negative edge noise, greatly so when happening on a diagonal edge. The strong erosiveness in acute corners of JC caused by the A(17-20) windows causes negative noise to ripple propagate in front of the eroding edge. Internal Noise occurs when a pixel internal to the image is missing. PSTA and CWSI algorithms do not erode the edges of single pixel internal holes. The AFP3 and JC algorithms erode these holes and produce large circles around them. One can identify single pixel holes from the skeleton produced by the PSTA and CWSI algorithms. AFP3 or JC it is often difficult to determine the size of the hole which caused the circular skeleton.

• Sensitivity to Rotation: All of the algorithms are basically insensitive to rotation, most showing only minor variation. PSTA is the only algorithm which is perfectly insensitive to 90° rotations due to their symmetric nature. The CWSI algorithm shows greatly varying skeletons for such objects rotated by 45°. One noticeable effect of 45° rotation is the change in the noise sensitivity of some of the algorithms. Both the AFP3 and JC algorithms become more sensitive to negative edge noise on diagonal lines. These two algorithms are potentially sensitive to rotation of irregular shaped objects.

CONCLUSION:

This discrepancy between different algorithms in various fields with the image being thinned. But the relative performance of the algorithms, as general trends, were reported in regards to skeleton quality, rough iteration count, sensitivity to noise and rotation. The measure of speed per iteration, however, is left to the hardware being used.

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